

# New in CoCoA-5.2.2 and CoCoALib-0.99560

for SC-Square



<http://cocoa.dima.unige.it/>

J. Abbott

& A.M. Bigatti

INdAM-COFUND Marie Curie Fellow & Università di Genova

The **CoCoA** project began in 1987 under the lead of Prof. L. Robbiano. The aim was to create a *mathematician-friendly* software laboratory for studying **Computational Commutative Algebra** (multivariate polynomials).

Available as open-source software: **2 main components**

- **CoCoALib** — C++ library
- **CoCoA-5** — interactive system

Main new features in CoCoALib-0.99560 and CoCoA-5.2.2

- interrupt handling and **timeout** capability
- global **verbose** option (user-settable verbosity level)
- minimal polynomials in quotients by 0-dim ideals
  - → radical, primary decomposition, tests for maximal or primary
- efficient **hypersurface implicitization**
- improved **Gröbner fan** operations (needs **GFanLib**)
- prototype interface with **MathSAT**

# Interrupt Mechanism: example C++ program

```
void LongComputation()
{
    ...
    for (int i=1; i < n; ++i) // MAIN LOOP
        { CheckForInterrupt("LongComputation"); // arg gives context info
            ...
        }
    ...
}

void program()
{
    ...
    SignalWatcher MonitorSIGINT(SIGINT); // RAI object
    try { LongComputation(); }
    catch (const InterruptedBySignal& intr)
    { PrintInFrame(cout, intr); /*handle the interrupt*/ }
}
```

# Timeout Mechanism: example C++ program

```
// New fn to add "timeout" feature to existing fn:  
vector<RingElem> RGBasisTimeout(const ideal& I, double Tmax)  
{  
    CpuTimeLimit timeout(Tmax);  
    return ReducedGBasis(I); // <-- this fn must call CheckForInterrupt  
}  
  
void program()  
{  
    GlobalManager CoCoAFoundations;  
    ...  
    ideal I = ideal(f1,f2,f3);  
    // Next line will throw InterruptedByTimeout if timeout occurs:  
    vector<RingElem> RGB = RGBasisTimeout(I, 3.0); // max 3.0 seconds  
}
```

## Timings for MinPolyQuot

- 0-dim ideal (gen. by dense random polys)
- dense random element in span of “quotient basis”
- in ring  $\mathbb{Q}[x, y, z]$ ; random coeffs are in range  $-9 \dots 9$

Deg	Time	Eliminate
3	1.4	45
4	28	14000+
5	295	—
6	2050	—
7	11600	—

Time is worst of 5 trials

## Timings for Primary Decomposition

Randomly generated zero-dimensional ideals in  $\mathbb{Q}[x, y, z]$

### Favourable case

$$\langle 29x^3y^3 + 94yz^5 + 99x^4, -36y^3z^3 - 67z^6 - 3x^4y, 19x^3y^3 + 97x^2z^2 - 85y^2 \rangle$$

CoCoA took 5.6s

Singular took 1600s

### Unfavourable case

$$\langle -11x^5 - 10x^4y + 12y^3z, -14z^4 + 15y^3 + 13yz, 9xz^4 + x^3y + 2y^3z \rangle$$

CoCoA took 45s

Singular took 3.3s

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Web site: <http://cocoa.dima.unige.it/>

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### Interim downloads:

- CoCoALib v. 0.99555 (August 2017)
- CoCoA v. 5.2.1 (August 2017)

### Imminent stable downloads:

- CoCoALib v. 0.99560 (expected September 2017)
- CoCoA v. 5.2.2 (expected September 2017)

Also... [redmine](#) (bug/feature tracker), & other useful bits and bobs.

# CoCoA and MathSAT

Two actors of the **SC<sup>2</sup> project**:

- **MathSAT**: SMT solver (Trento)
- **CoCoALib/CoCoA-5**: Computer Algebra System (Genova)

One SC<sup>2</sup> deliverable: prototype of communication between them

- ① **MathSAT** using **CoCoALib**'s RingTwinFloat arithmetic  
(instead of arbitrary precision rationals, GMP mpq)
- ② **MathSAT** using **CoCoALib** for systems of polynomial inequalities  
(future! hopefully)
- ③ enabling **CoCoALib** to call some of **MathSAT**'s functions
- ④ using **CoCoA-5** as a handy interface for **MathSAT**  
(through CoCoALib)

## (3) CoCoAlib calling MathSAT: C++ program excerpt

```

ring P = NewPolyRing(QQ, symbols("x,y"));
MathSAT::env E;

matrix M = NewDenseMat(QQ, 2, 3); // (2x3 matrix)
SetEntry(M,0,0, 3); SetEntry(M,0,1, 1); SetEntry(M,0,2, -2);
SetEntry(M,1,0, 1); SetEntry(M,1,1, -1); SetEntry(M,1,2, 0);
MathSAT::AddLeq0(E, M);           // 3*x -y -2 <= 0
                                // x -y      <= 0
M = NewDenseMat(QQ, 1, 3); SetEntry(M,0,0, 1); // (1x3 matrix)
MathSAT::AddNeq0(E, M);          // x          != 0

// polynomial syntax:
RingElem x(P, "x"), y(P, "y");
MathSAT::AddLeq0(E, x -9);       // x      -9 <= 0
MathSAT::AddEq0(E, x -y);        // x -y      = 0
MathSAT::AddLt0(E, 2*x-1);       // 2*x      -1 < 0

cout << "A solution is " << MathSAT::LinSolve(E) << endl; // -> 1/4, 1/4

```

## (4) CoCoA-5 calling MathSAT: interactive call

We represent a system as a record of matrices (first prototype):

```
system :=  
record[leq0 := matrix([[1,2,3, 4], // x +2*y +3*z +4 <= 0  
                      [9,8,7, 0]]), // 9*x +8*y +7*z <= 0  
      neq0 := matrix([[1,0,0, 0]]) // x <> 0  
    ];  
  
sol := MSatLinSolve(system); sol;  
// gives [[1], [4/5], [-11/5]]  
  
// verify:  
sol1 := ConcatVer(sol, matrix([[1]])); //--> [[1], [4/5], [-11/5], [1]]  
system.leq0 * sol1; //--> 0, 0 <= 0  
system.neq0 * sol1; //--> 1 <> 0
```

Continuation:

```
// solution was  [[1], [4/5], [-11/5]]
// now we add new constraints:
system.eq0 := RowMat([1,1,0, 4]);    //  x +y +4 = 0
system.lt0 := RowMat([0,1,0, 0]);    //      y      < 0

sol := MSatLinSolve(system);  sol;
// gives  [[-2], [-2], [-2/7]])

// verify:
sol1 := ConcatVer(sol, RowMat([1]));  //-->  [[-2], [-2], [-2/7], [1]]
system.leq0 * sol1;  //--> -20/7, -36  <= 0
system.neq0 * sol1; //--> -2          <> 0
system.eq0  * sol1; //-->  0          = 0
system.lt0  * sol1; //--> -2          < 0
```